

2000mm Ultrasonic Fuel Level Sensor UFL2000

Specification



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I. Overview

UFL2000 fuel level meter is a sensing device that uses ultrasonic detection technology to measure the non-contact liquid level of fuel and liquid substances. Compared with traditional testing equipment, UFL2000 fuel level meter has high measurement accuracy and is easy to use. It can be externally installed (without destroying the container structure), and can be connected to networked devices for network monitoring and management. The ultrasonic fuel quantity monitoring sensor is optimized for vehicle monitoring mode. It can adapt to vehicles running or stationary at various speeds on various roads, and can output more stable data for other liquids loaded on the vehicle. UFL2000 fuel level meter is referred to as sensor.

II. Product Features

Non-contact measurement, no need to change the shape of the container, no need to polish the surface paint layer of the container;

Metal casing, internal circuit potting treatment, rainproof design, suitable for outdoor environment; built-in powerful magnet, external waterproof adhesive, easy to install, fixed and firm;

Wide voltage operation, DC 12~48V power supply, suitable for all kinds of vehicles;

RS232 output interface, compatible with various sensor signal connections;

High-frequency ultrasonic testing, high solid penetration, suitable for containers of various materials such as metal and plastic

High stability measurement output, built-in anti-interference data processing model, intelligent filtering, compensation for environmental interference

High-precision measurement output, built-in high-precision calculation model, millimeter-scale measurement resolution

III. Application

Vehicle fuel quantity monitoring

Liquid level measurement

Container water level monitoring

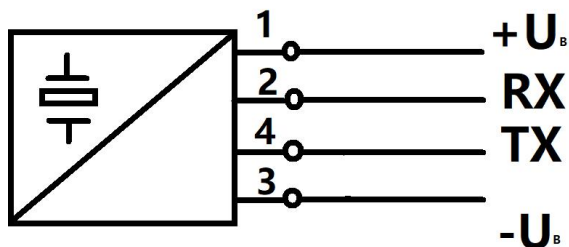
IV: Parameters

| | |
|---|------------------------------------|
| Technical data | |
| General Specifications | |
| Sensing distance | 20...2000mm |
| Adjustment range | 20...2000mm |
| Unusable area | 0...20mm |
| Standard target plate | 100mm×100mm |
| Transducer frequency About | 2 MHz |
| Response delay About | 85 ms |
| Indicators/Operating means | |
| LED yellow | solid: NO LED flash: |
| LED red | flashing: |
| Electrical specifications | |
| Operating voltage U_B | 5...12 VDC ripple10%ss |
| No-load supply current | $\leq 20\text{mA}$ |
| Output | |
| Output type | 1 digital output RS485 or UART/TTL |
| Resolution | |
| Deviation of the characteristic curve | $\pm 1\%$ of full-scale value |
| Repeat accuracy | $\pm 0.1\%$ of full-scale value |
| Load impedance | $> 1\text{k Ohm}$ |

| | |
|---|---------------------------------------|
| Maximum switching current | mA |
| Temperature influence | ±1.5% of full-scale value |
| Ambient conditions | |
| Ambient temperature | -25...70°C |
| Storage temperature | -40...85°C |
| Mechanical specifications | |
| Protection grade | IP68 |
| Connection | PVC cable,4-CABLE |
| Material | |
| Housing | PBT OR FRP |
| Transducer | Epoxy resin/hollow; Polyurethane foam |
| Weight | 30g |
| Compliance with standards and Directives | |
| Standard conformity | CE/ CCC |

V. Wire connection

1 RD=RED
 2 GN=GREEN
 3 BK=BLACK
 4 YL=YELLOW



VI: MODBUS Communication

MODBUS RTU communication protocol

1. The hardware uses RS-485/422/UART TTL, master-slave half/full duplex communication, with the master calling the slave address and the slave responding to communication.

2. Data frame 10 bits, 1 start bit, 8 data bits, 1 stop bit, no checksum.

Baud rate 9600 19200 115200 (default is 9600)

3. Function code 03H: Read register value

Host sends:

| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----|-----|-----------------------------|----------------------------|-----------------------------------|----------------------------------|-------------------|--------------------|
| ADR | 03H | Starting register high byte | Starting register low byte | High number of registers in bytes | Low number of registers in bytes | CRC code low byte | CRC code high byte |

1st byte ADR: Slave address code (x01~0xFE default 0x01)

Second byte 03H: Read register value function code

3rd and 4th bytes: starting address of the register to be read

5th and 6th bytes: number of registers to be read

7th and 8th bytes: CRC16 checksum from bytes 1 to 6

When the slave receives correctly, it sends back:

| 1 | 2 | 3 | 4、5 | 6、7 | | M-1、M | M+1 | M+2 |
|-----|-----|-------------|-----------------|-----------------|-------|-----------------|-------------------|--------------------|
| ADR | 03H | total bytes | Register Data 1 | Register Data 2 | ◦ ◦ ◦ | Register data M | CRC code low byte | CRC code high byte |

1st byte ADR: Slave address code

Second byte 03H: Return the read function code

The total number of bytes from 4 to M (including 4 and M) in the third byte

4th to M bytes: Register data

M+1 and M+2 bytes: CRC16 checksum from byte 1 to M

4. Function code 06H: Write a single register value

Host sends:

| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----|----|----------------------------|---------------------------|----------------|---------------|-------------------|--------------------|
| ADR | 06 | Register address high byte | Low byte register address | High byte data | Low byte data | CRC code low byte | CRC code high byte |

When the slave receives correctly, it sends back:

| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----|----|--------------------|-------------------|----------------|---------------|-------------------|--------------------|
| ADR | 06 | Register high byte | Register low byte | High byte data | Low byte data | CRC code low byte | CRC code high byte |

When the slave receives an error, it sends back:

| 1 | 2 | 3 | 4 | 5 |
|-----|-----|--------------------|-------------------|--------------------|
| ADR | 86H | Error message code | CRC code low byte | CRC code high byte |

1st byte ADR: Slave address code (=001~254)

Byte 1 86H: Function code for writing register value error

3rd byte information code: see information code table

4th and 5th bytes: CRC16 checksum from bytes 1 to 3

5. Register Definition Table: (Note: Register addresses are encoded in hexadecimal, with the higher bits coming first)

| Register addresses | Content Description | only read | only write | Register addresses | Content Description | only read | only write |
|--------------------|---|-----------|------------|--------------------|---|-----------|------------|
| 1000 | Measurement distance (mm) (2-byte high-order) | ✓ | | 1001 | Instantaneous temperature value (°C) (where the high bit is the positive and negative indicator bit, and the temperature is 1 below zero, otherwise it is zero; the low bit is the temperature value) | ✓ | |
| | | | | 100E | Device address (default 01H) (value range 0x00-0FA) | | |
| 1010 | Baud rate (default 9600; values: 01-9600, 02--19200, 03-115200) | | | 1011 | Reserved | | |
| 1012 | Liquid types (01 water, 02 diesel, 03 gasoline) | | | 0019 | Reserved | | |
| 001A | Reserved | | | 001B | Reserved | | |

(1) Example of reading a single register: reading distance (current sensor address is 0x01)

send out:

01 03 10 00 00 01 80 CA

return:

01 03 02 06 78 BB C6

The two red bytes indicate that the current measurement value is 1656 (0x0678=1656 in millimeters)

(2) Example of reading multiple registers: reading distance and temperature (current sensor address is 0x01)

send out:

01 03 10 00 00 02 C0 CB

return:

01 03 04 07 78 00 16 FA 90

The two red bytes represent: current distance of 1912mm (0x0778), temperature of 22 °C (0x0016);

(3) Example: Write baud rate

send out:

01 06 10 10 00 01 4D 0F

Write baud rate 01 (9600)

return:

01 06 10 10 00 01 4D 0F

Returning 01 indicates successful writing

(4) Example: Read the currently set liquid type

Send:

01 03 10 12 00 01 20 CF

(5) Example: Setting the type of liquid to be measured

01 06 10 12 00 01 CE CF

01 Water, 02 Diesel, 03 Gasoline

VII. Installation

There is a set of install shell for this fuel level sensor, it include shell A and shell B, as picture:



- 1/ First, use fuel level sensor to locate a point on the bottom of the tank and mark it, make sure the signal is good.
- 2/ Stick the Shell A with strong glue at the marked point on the bottom of tank.
- 3/ Put the fuel level sensor into the Shell A, pay attention that there is no any bubbles and gap between the sensor and tank surface, the best way is to put some coupling agent on the sensor surface when put the sensor into Shell A.
- 4/ Screw up Shell B to Shell A, fix the sensor tightly.

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